# Universitext

Editorial Board (North America):

S. Axler K.A. Ribet Claudio Procesi

## Lie Groups

# An Approach through Invariants and Representations



Claudio Procesi Dipartimento di Matematica "G. Castelnouvo" Università di Roma "La Sapienza" 00185 Rome Italy procesi@mat.uniromal.it

Editorial Board (North America):

S. Axler Mathematics Department San Francisco State University San Francisco, CA 94132 USA axler@sfsu.edu K.A. Ribet Mathematics Department University of California at Berkeley Berkeley, CA 94720-3840 USA ribet@math.berkeley.edu

Mathematics Subject Classification 2000: Primary: 22EXX, 14LXX Secondary: 20GXX, 17BXX

Library of Congress Cataloging-in-Publication Data

Procesi, Claudio.
An approach to Lie Theory through Invariants and Representations / Claudio Procesi.
p. cm.— (Universitext)
Includes bibliographical references and index.
ISBN-13: 978-0-387-26040-2 (acid-free paper)
ISBN-10: 0-387-26040-4 (acid-free paper)
1. Lie groups. 2. Invariants. 3. Representations of algebras. I. Title.
QA 387.P76 2005
512' 482—dc22
2005051743

ISBN-10: 0-387-26040-4 e-ISBN: 0-387-28929-1 Printed on acid-free paper. ISBN-13: 978-0387-26040-2

©2007 Springer Science+Business Media, LLC

All rights reserved. This work may not be translated or copied in whole or in part without the written permission of the publisher (Springer Science+Business Media LLC, 233 Spring Street, New York, NY 10013, USA), except for brief excerpts in connection with reviews or scholarly analysis. Use in connection with any form of information storage and retrieval, electronic adaptation, computer software, or by similar or dissimilar methodology now known or hereafter developed is forbidden.

The use in this publication of trade names, trademarks, service marks and similar terms, even if they are not identified as such, is not to be taken as an expression of opinion as to whether or not they are subject to proprietary rights.

Printed in the United States of America. (TXQ)

987654321

springer.com

To the ladies of my life, Liliana, Silvana, Michela, Martina

## Contents

	In	troduction	cix
	C	onventional Notationsxx	iii
1	Ge	meral Methods and Ideas	1
	1	Groups and Their Actions	1
		1.1 Symmetric Group	1
		1.2 Group Actions	2
	2	Orbits, Invariants and Equivariant Maps	4
		2.1 Orbits	4
		2.2 Stabilizer	5
		2.3 Invariants	7
		2.4 Basic Constructions	7
		2.5 Permutation Representations	8
		2.6 Invariant Functions	10
		2.7 Commuting Actions	11
	3	Linear Actions, Groups of Automorphisms, Commuting Groups	11
		3.1 Linear Actions	11
		3.2 The Group Algebra	13
		3.3 Actions on Polynomials	15
		3.4 Invariant Polynomials	16
		3.5 Commuting Linear Actions	17
2	Sy	mmetric Functions	19
	1	Symmetric Functions	19
		1.1 Elementary Symmetric Functions	19
		1.2 Symmetric Polynomials	21
	2	Resultant, Discriminant, Bézoutiant	22
		2.1 Polynomials and Roots	22

		2.2 Resultant	25
		2.3 Discriminant	27
	3	Schur Functions	28
		3.1 Alternating Functions	28
		3.2 Schur Functions	29
		3.3 Duality	31
	4	Cauchy Formulas	31
		4.1 Cauchy Formulas	31
	5	The Conjugation Action	34
	-	51 Conjugation	34
		en eenjuguden	
2	ть	come of Algobraic Forms	27
3	1	Differential Operators	וכ 27
	1	1.1 Wayl Algebra	37 27
	ſ	The Arenhald Method Delevingting	31 10
	2	The Aronnold Method, Polarization	40
		2.1 Polarizations	40
		2.2 Restitution	41
		2.3 Multilinear Functions	43
		2.4 Aronhold Method	44
	3	The Clebsch–Gordan Formula	45
		3.1 Some Basic Identities	45
	4	The Capelli Identity	48
		4.1 Capelli Identity	48
	5	Primary Covariants	52
		5.1 The Algebra of Polarizations	52
		5.2 Primary Covariants	53
		5.3 Cayley's $\Omega$ Process	55
4	Lie	e Algebras and Lie Groups	59
	1	Lie Algebras and Lie Groups	59
		1.1 Lie Algebras	59
		1.2 Exponential Map	61
		1.3 Fixed Points, Linear Differential Operators	63
		1.4 One-Parameter Groups	65
		1.5 Derivations and Automorphisms	68
	2	Lie Groups	69
		2.1 Lie Groups	69
	3	Correspondence between Lie Algebras and Lie Groups	71
		3.1 Basic Structure Theory	71
		3.2 Logarithmic Coordinates	75
		3.3 Frobenius Theorem	77
		3.4 Simply Connected Groups	80
		3.5 Actions on Manifolds	81
		3.6 Polarizations	82

		3.7	Homogeneous Spaces	83
	4	Basi	ic Definitions	86
		4.1	Modules	86
		4.2	Abelian Groups and Algebras	87
		4.3	Nilpotent and Solvable Algebras	88
		4.4	Killing Form	89
	5	Basi	ic Examples	90
		5.1	Classical Groups	90
		5.2	Quaternions	92
		5.3	Classical Lie Algebras	93
	6	Basi	ic Structure Theorems for Lie Algebras	95
		6.1	Jordan Decomposition	95
		6.2	Engel's Theorem	95
		6.3	Lie's Theorem	96
		6.4	Cartan's Criterion	97
		6.5	Semisimple Lie Algebras	98
		6.6	Real Versus Complex Lie Algebras	98
	7	Con	nparison between Lie Algebras and Lie Groups	99
		7.1	Basic Comparisons	99
5	Те	nsor	Algebra	101
÷	1	Tens	sor Algebra	101
	-	1.1	Functions of Two Variables	101
		1.2	Tensor Products	102
		1.3	Bilinear Functions	103
		1.4	Tensor Product of Operators	103
		1.5	Special Isomorphisms	105
		1.6	Decomposable Tensors	106
		1.7	Multiple Tensor Product	106
		1.8	Actions on Tensors	108
	2	Svn	metric and Exterior Algebras	109
		2.1	Symmetric and Exterior Algebras	109
		2.2	Determinants	110
		2.3	Symmetry on Tensors	111
	3	Bili	near Forms	114
		3.1	Bilinear Forms	114
		3.2	Symmetry in Forms	114
		3.3	Isotropic Spaces	115
		3.4	Adjunction	116
		3.5	Orthogonal and Symplectic Groups	117
		3.6	Pfaffian	118
		3.7	Quadratic Forms	119
		3.8	Hermitian Forms	121
		3.9	Reflections	122

x	Contents

		3.10	Topology of Classical Groups	124
	4	Cliff	ford Algebras	125
		4.1	Clifford Algebras	125
		4.2	Center	129
		4.3	Structure Theorems	130
		4.4	Even Clifford Algebra	131
		4.5	Principal Involution	133
	5	The	Spin Group	133
		5.1	Spin Groups	133
	6	Basi	c Constructions on Representations	137
		6.1	Tensor Product of Representations	137
		6.2	One-dimensional Representations	138
	7	Univ	versal Enveloping Algebras	139
		7.1	Universal Enveloping Algebras	139
		7.2	Theorem of Capelli	142
		7.3	Free Lie Algebras	143
6	Sei	misin	nple Algebras	145
	1	Sem	nisimple Algebras	145
		1.1	Semisimple Representations	145
		1.2	Self-Adjoint Groups	146
		1.3	Centralizers	147
		1.4	Idempotents	149
		1.5	Semisimple Algebras	150
		1.6	Matrices over Division Rings	151
		1.7	Schur's Lemma	151
		1.8	Endomorphisms	152
		1.9	Structure Theorem	153
	2	Isot	ypic Components	154
		2.1	Semisimple Modules	154
		2.2	Submodules and Quotients	156
		2.3	Isotypic Components	156
		2.4	Reynold's Operator	157
		2.5	Double Centralizer Theorem	158
		2.6	Products	159
		2.7	Jacobson Density Theorem	161
		2.8	Wedderburn's Theorem	162
	3	Prin	nitive Idempotents	162
		3.1	Primitive Idempotents	162
		3.2	Real Algebras	165

7	Alg	gebra	aic Groups	167
	1	Alge	ebraic Groups	167
		1.1	Algebraic Varieties	167
		1.2	Algebraic Groups	169
		1.3	Rational Actions	171
		1.4	Tensor Representations	172
		1.5	Jordan Decomposition	173
		1.6	Lie Algebras	174
	2	Ouo	tients	175
		2.1	Ouotients	175
	3	Line	early Reductive Groups.	179
	-	3.1	Linearly Reductive Groups	179
		3.2	Self-adjoint Groups	182
		3.3	Tori	183
		3.4	Additive and Unipotent Groups	184
		3.5	Basic Structure Theory	186
		3.6	Reductive Groups	188
	4	Bor	el Subgrouns	190
	•	41	Borel Subgroups	190
			Dolor Subgroups	170
8	Gr	oup	Representations	195
	1	Cha	racters	195
		1.1	Characters	195
		1.2	Haar Measure	196
		1.3	Compact Groups	198
		1.4	Induced Characters	200
	2	Mat	rix Coefficients	201
	_	2.1	Representative Functions	201
		2.2	Preliminaries on Functions	203
		2.3	Matrix Coefficients of Linear Groups	205
	3	The	Peter–Weyl Theorem	205
	-	3.1	Operators on a Hilbert Space	205
		32	Peter-Weyl Theorem	213
		33	Fourier Analysis	214
		34	Compact Lie Groups	216
	4	Ren	resentations of Linearly Reductive Groups	217
	•	4.1	Characters for Linearly Reductive Groups	217
	5	Indi	iction and Restriction	221
	-	5.1	Clifford's Theorem	221
		5.2	Induced Characters	222
		5.3	Homogeneous Spaces	223
	6	The	Unitary Trick	224
	U	61	Polar Decomposition	224
		6.2	Cartan Decomposition	225
		0.2		

		6.3 Classical Groups	. 229
	7	Hopf Algebras and Tannaka-Krein Duality	. 230
		7.1 Reductive and Compact Groups	. 230
		7.2 Hopf Algebras.	. 231
		7.3 Hopf Ideals	. 235
		*	
9	Te	nsor Symmetry	241
	1	Symmetry in Tensor Spaces	. 241
		1.1 Intertwiners and Invariants	. 241
		1.2 Schur–Weyl Duality	. 243
		1.3 Invariants of Vectors	. 244
		1.4 First Fundamental Theorem for the Linear Group (FFT)	. 245
	2	Young Symmetrizers	. 247
		2.1 Young Diagrams	. 247
		2.2 Symmetrizers	. 248
		2.3 The Main Lemma	. 250
		2.4 Young Symmetrizers 2	. 252
		2.5 Duality	. 254
	3	The Irreducible Representations of the Linear Group 1	. 255
		3.1 Representations of the Linear Groups	. 255
	4	Characters of the Symmetric Group	. 256
		4.1 Character Table	. 256
		4.2 Frobenius Character	. 262
		4.3 Molien's Formula	. 263
	5	The Hook Formula	. 266
		5.1 Dimension of $M_{\lambda}$	. 266
		5.2 Hook Formula	. 267
	6	Characters of the Linear Group	. 268
		6.1 Tensor Character	. 268
		6.2 Character of $S_{\lambda}(V)$	. 269
		6.3 Cauchy Formula as Representations	. 270
		6.4 Multilinear Elements	. 271
	7	Polynomial Functors	. 273
		7.1 Schur Functors	. 273
		7.2 Homogeneous Functors	. 274
		7.3 Plethysm	277
	8	Representations of the Linear and Special Linear Groups	. 278
		8.1 Representations of $SL(V)$ , $GL(V)$	278
		8.2 The Coordinate Ring of the Linear Group	279
		8.3 Determinantal Expressions for Schur Functions	
	~	8.4 Skew Cauchy Formula	281
	9	Branching Rules for $S_n$ , Standard Diagrams	282
		9.1 Mumaghan's Kule	282
		9.2 Branching Rule for $S_n$	285

	10	Bran	nching Rules for the Linear Group, Semistandard Diagrams	288
		10.1	Branching Rule	288
		10.2	Pieri's Formula	289
		10.3	Proof of the Rule	290
10	Ser	nisin	pole Lie Groups and Algebras	293
	1	Sem	isimple Lie Algebras	293
		1.1	$sl(2,\mathbb{C})$	293
		1.2	Complete Reducibility	295
		1.3	Semisimple Algebras and Groups.	297
		1.4	Casimir Element and Semisimplicity	298
		1.5	Jordan Decomposition	300
		1.6	Levi Decomposition	301
		1.7	Ado's Theorem	308
		1.8	Toral Subalgebras	309
		1.9	Root Spaces	312
	2	Root	t Systems	314
	-	2.1	Axioms for Root Systems	314
		2.2	Regular Vectors	316
		2.3	Reduced Expressions	319
		2.4	Weights	322
		2.5	Classification	324
		2.6	Existence of Root Systems	329
		2.7	Coxeter Groups	330
	3	Con	struction of Semisimple Lie Algebras	332
	2	3.1	Existence of Lie Algebras	332
		3.2	Uniqueness Theorem	336
	4	Clas	sical Lie Algebras	337
	•	4.1	Classical Lie Algebras	337
		42	Borel Subalgebras	341
	5	Hioł	hest Weight Theory	341
	2	51	Weights in Representations Highest Weight Theory	341
		5.2	Highest Weight Theory	343
		53	Fxistence of Irreducible Modules	345
	6	Sem	isimple Groups	347
	Ŭ	6.1	Dual Hopf Algebras	347
		6.2	Parabolic Subgroups	351
		63	Borel Subgroups	354
		6.4	Bruhat Decomposition	356
		6.5	Bruhat Order	362
		6.6	Quadratic Equations	367
		67	The Weyl Group and Characters	370
		6.8	The Fundamental Group	371
		60	Reductive Groups	375
		0.7		515

		6.10 Automorphisms	376
	7	Compact Lie Groups	377
		7.1 Compact Lie Groups	377
		7.2 The Compact Form	378
		7.3 Final Comparisons	380
11	Inv	variants	385
	1	Applications to Invariant Theory	385
	-	1.1 Cauchy Formulas	385
		1.2 FFT for $SL(n, \mathbb{C})$	387
	2	The Classical Groups	389
	_	2.1 FFT for Classical Groups	389
	3	The Classical Groups (Representations)	392
	U	3.1 Traceless Tensors	392
		3.2 The Envelope of $O(V)$	396
	4	Highest Weights for Classical Groups	397
		4.1 Example: Representations of <i>SL(V)</i>	397
		4.2 Highest Weights and <i>U</i> -Invariants	398
		4.3 Determinantal Loci	399
		4.4 Orbits of Matrices	400
		4.5 Cauchy Formulas	403
		4.6 Bruhat Cells	404
	5	The Second Fundamental Theorem (SFT)	404
		5.1 Determinantal Ideals	404
		5.2 Spherical Weights	409
	6	The Second Fundamental Theorem for Intertwiners	410
		6.1 Symmetric Group	410
		6.2 Multilinear Spaces	412
		6.3 Orthogonal and Symplectic Group	413
		6.4 Irreducible Representations of $Sp(V)$	415
		6.5 Orthogonal Intertwiners	416
		6.6 Irreducible Representations of SO(V)	419
		6.7 Fundamental Representations	422
		6.8 Invariants of Tensor Representations	425
	7	Spinors	425
		7.1 Spin Representations	426
		7.2 Pure Spinors	427
		7.3 Triality	434
	8	Invariants of Matrices	435
		8.1 FFT for Matrices	435
		8.2 FFT for Matrices with Involution	436
		8.3 Algebras with Trace	438
		8.4 Generic Matrices	440
		8.5 Trace Identities	441

		8.6	Polynomial Identities	445
		8.7	Trace Identities with Involutions	446
		8.8	The Orthogonal Case	449
		8.9	Some Estimates	451
		8.10	Free Nil Algebras	452
		8.11	Cohomology	453
	9	The	Analytic Approach to Weyl's Character Formula	456
		9.1	Weyl's Integration Formula	456
	10	Char	racters of Classical Groups	461
		10.1	The Symplectic Group	461
		10.2	Determinantal Formula	465
		10.3	The Spin Groups: Odd Case	468
		10.4	The Spin Groups: Even Case	469
		10.5	Weyl's Character Formula	469
12	Ты	hlean	IV.	475
14	1	The	Robinson-Schensted Correspondence	475
	1	1 1	Insertion	475
		1.1	Knuth Fauivalence	479
	2	Ien d	de Taquin	481
	-	21	Slides	481
		$\frac{2.1}{2.2}$	Vacating a Box	487
	3	Dua	1 Knuth Equivalence	488
	4	Form	nal Schur Functions	494
	•	4.1	Schur Functions	494
	5	The	Littlewood–Richardson Rule	495
	U	5.1	Skew Schur Functions	495
		5.2	Clebsch–Gordan Coefficients	496
		5.3	Reverse Lattice Permutations	497
		0.0		
13	C4-		A Manageria la	400
13	512		dard Monomials	499
	1		Standard Manamiala	499
	2	1.1 Dl#a	Standard Monomials	499
	4	Pluc	Combinatorial America h	501
		2.1	Streightoning Algorithm	504
		2.2		505
	2	2.3 The	Greesmann Variaty and Its Schubert Calls	505
	3	2 1	Grassmann Varieties	500
		2.1	Sobubert Calls	500
		3.2 2.2	Divideor aquations	512
		3.3 2 1		517
		5.4 25	Plags	514
		5.5 2.6	D-010115	513
		5.0	Stanuaru Mullulliais	517

4	Dou	ble Tableaux	518
	4.1	Double Tableaux	518
	4.2	Straightening Law	519
	4.3	Quadratic Relations	523
5	Rep	resentation Theory	525
	5.1	U Invariants	525
	5.2	Good Filtrations	529
	5.3	SL(n)	531
	5.4	Branching Rules	532
	5.5	SL(n) Invariants	533
6	Cha	racteristic Free Invariant Theory	533
	6.1	Formal Invariants	533
	6.2	Determinantal Varieties	535
	6.3	Characteristic Free Invariant Theory	536
7	Rep	resentations of S <sub>n</sub>	538
	7.1	Symmetric Group	538
	7.2	The Group Algebra	540
	7.3	Kostka Numbers	541
8	Sec	ond Fundamental Theorem for GL and S <sub>m</sub>	541
	8.1	Second Fundamental Theorem for the Linear Group	541
	8.2	Second Fundamental Theorem for the Symmetric Group	542
	8.3	More Standard Monomial Theory	542
	8.4	Pfaffians	545
	8.5	Invariant Theory	548
		·	
14 H	ilhert	Theory	553
1	The	Finiteness Theorem	553
1	1 1	Finite Generation	553
2	Hill	pert's 14 <sup>th</sup> Problem	554
2	2.1	Hilbert's 14 <sup>th</sup> Problem	554
3	- <u>2</u> .1 Ouc	ntient Varieties	555
4	Hill	pert-Mumford Criterion	556
•	4 1	Projective Quotients	556
5	The	Cohen-Macaulay Property	559
0	5 1	Hilbert Series	559
	5.2	Cohen-Macaulay Property	561
	5.2		201
15 B	norv	Forms	563
15 10	Con	roring	563
1	11	Covariants	563
	1.1	Transvectants	565
	1.2	Source	566
2	- 1.5 - Cor	nnutational Algorithms	568
2	2.1	Recursive Computation	568

3	2.2       Symbolic Method       572         Hilbert Series       575         2.1       Hilbert Series
4	5.1 Hildert Series       575         Forms and Matrices       579         4.1 Forms and Matrices       579
Biblio	g <b>raphy</b>
Index	of Symbols
Subje	t Index

#### Introduction

The subject of Lie groups, introduced by Sophus Lie in the second half of the nineteenth century, has been one of the important mathematical themes of the last century. Lie groups formalize the concept of continuous symmetry, and thus are a part of the foundations of mathematics. They also have several applications in physics, notably quantum mechanics and relativity theory. Finally, they link with many branches of mathematics, from analysis to number theory, passing through topology, algebraic geometry, and so on.

This book gives an introduction to at least the main ideas of the theory. Usually, there are two principal aspects to be discussed. The first is the description of the groups, their properties and classifications; the second is the study of their representations.

The problem that one faces when introducing representation theory is that the material tends to grow out of control quickly. My greatest difficulty has been to try to understand when to stop. The reason lies in the fact that one may represent almost any class of algebraic if not even mathematical objects. In fact it is clear that even the specialists only master part of the material.

There are of course many good introductory books on this topic. Most of them however favor only one aspect of the theory. I have tried instead to present the basic methods of Lie groups, Lie algebras, algebraic groups, representation theory, some combinatorics and basic functional analysis, which then can be used by the various specialists. I have tried to balance general theory with many precise concrete examples.

This book started as a set of lecture notes taken by G. Boffi for a course given at Brandeis University. These notes were published as a "Primer in Invariant Theory" [Pr]. Later, H. Kraft and I revised these notes, which have been in use and are available on Kraft's home page [KrP]. In these notes, we present classical invariant theory in modern language. Later, E. Rogora and I presented the combinatorial approach to representations of the symmetric and general linear groups [PrR]. In past years, while teaching introductory courses on representation theory, I became convinced that it would be useful to expand the material in these various expositions to give an idea of the connection with more standard classical topics, such as the theory of Young symmetrizers and Clifford algebras, and also not to restrict to classical groups but to include general semisimple groups as well.

The reader will see that I have constantly drawn inspiration from the book of H. Weyl, *Classical Groups* [W]. On the other hand it would be absurd and quite impossible to *update* this classic.

In his book Weyl stressed the relationship between representations and invariants. In the last 30 years there has been a renewed interest in classical methods of invariant theory, motivated by problems of geometry, in particular due to the ideas of Grothendieck and Mumford on moduli spaces. The reader will see that I do not treat geometric invariant theory at all. In fact I decided that this would have deeply changed the nature of the book, which tries to always remain at a relatively elementary level, at least in the use of techniques outside of algebra. Geometric invariant theory is deeply embedded in algebraic geometry and algebraic groups, and several good introductions to this topic are available.

I have tried to explain in detail all the constructions which belong to invariant theory and algebra, introducing and using only the essential notions of differential geometry, algebraic geometry, measure theory, and functional analysis which are necessary for the treatment here. In particular, I have tried to restrict the use of algebraic geometry and keep it to a minimum, nevertheless referring to standard books for some basic material on this subject which would have taken me too long to discuss in this text. While it is possible to avoid algebraic geometry completely, I feel it would be a mistake to do so since the methods that algebraic geometry introduces in the theory are very powerful. In general, my point of view is that some of the interesting special objects under consideration may be treated by more direct and elementary methods, which I have tried to do whenever possible since a direct approach often reveals some special features which may be lost in a general theory. A similar, although less serious, problem occurs in the few discussions of homotopy theory which are needed to understand simply connected groups.

I have tried to give an idea of how 19<sup>th</sup>-century algebraists thought of the subject. The main difficulty we have in understanding their methods is in the fact that the notion of representation appears only at a later stage, while we usually start with it.

The book is organized into topics, some of which can be the subject of an entire graduate course. The organization is as follows.

The first chapter establishes the language of group actions and representations with some simple examples from abstract group theory. The second chapter is a quick look into the theory of symmetric functions, which was one of the starting points of the entire theory. First, I discuss some very classical topics, such as the resultant and the Bézoutiant. Next I introduce Schur functions and the Cauchy identity. These ideas will play a role much later in the character theory of the symmetric and the linear group.

Chapter 3 presents again a very classical topic, that of the theory of algebraic forms, à la Capelli [Ca].

In Chapter 4, I change gears completely. Taking as pretext the theory of polarizations of Capelli, I systematically introduce Lie groups and Lie algebras and start to prove some of the basic structure theorems. The general theory is completed in Chapter 5 in which universal enveloping algebras and free Lie algebras are discussed. Later, in Chapter 10 I treat semisimple algebras and groups. I complete the proof of the correspondence between Lie groups and Lie algebras via Ado's theorem. The rest of the chapter is devoted to Cartan–Weyl theory, leading to the classification of complex semisimple groups and the associated classification of connected compact groups.

Chapter 5 is quite elementary. I decided to include it since the use of tensor algebra and tensor notation plays such an important role in the treatment as to deserve some lengthy discussion. In this chapter I also discuss Clifford algebras and the spin group. This topic is completed in Chapter 11.

Chapter 6 is a short introduction to general methods of noncommutative algebra, such as Wedderburn's theorem and the double centralizer theorem. This theory is basic to the representation theory to be developed in the next chapters.

Chapter 7 is a quick introduction to algebraic groups. In this chapter I make fair use of notions from algebraic geometry, and I try to at least clarify the statements used, referring to standard books for the proofs. In fact it is impossible, without a rather long detour, to actually develop in detail the facts used. I hope that the interested reader who does not have a background in algebraic geometry can still follow the reasoning developed here.

I have tried to stress throughout the book the parallel theory of reductive algebraic and compact Lie groups. A full understanding of this connection is gained slowly, first through some classical examples, then by the Cartan decomposition and Tannaka duality in Chapter 8. This theory is completed in Chapter 10, where I associate, to a semisimple Lie algebra, its compact form. After this the final classification theorems are proved.

Chapter 8 is essentially dedicated to matrix coefficients and the Peter–Weyl theorem. Some elementary functional analysis is used here. I end the chapter with basic properties of Hopf algebras, which are used to make the link between compact and reductive groups.

Chapter 9 is dedicated to tensor symmetry, Young symmetrizers, Schur–Weyl duality and their applications to representation theory.

Chapter 10 is a short course giving the structure and classification of semisimple Lie algebras and their representations via the usual method of root systems. It also contains the corresponding theory of adjoint and simply connected algebraic groups and their compact forms.

Chapter 11 is the study of the relationship between invariants and the representation theory of classical groups. It also contains a fairly detailed discussion of spinors and terminates with the analytic proof of Weyl's character formula.

The last four chapters are complements to the theory. In Chapter 12 we discuss the combinatorial theory of tableaux to lead to Schützenberger's proof of the Littlewood–Richardson rule.

Chapter 13 treats the combinatorial approach to invariants and representations for classical groups. This is done via the theory of standard monomials, which is developed in a characteristic-free way, for some classical representations. Chapter 14 is a very short glimpse into the geometric theory, and finally Chapter 15 is a return to the past, to where it all started: the theory of binary forms.

Many topics could not find a place in this treatment. First, I had to restrict the discussion of algebraic groups to a minimum. In particular I chose giving proofs only in characteristic 0 when the general proof is more complicated. I could not elaborate on the center of the universal enveloping algebra, Verma modules and all the ideas relating to finite and infinite-dimensional representations. Nor could I treat the conjugation action on the group and the Lie algebra which contains so many deep ideas and results. Of course I did not even begin to consider the theory of real semisimple groups. In fact, the topics which relate to this subject are so numerous that this presentation here is just an invitation to the theory. The theory is quite active and there is even a journal entirely dedicated to its developments.

Finally, I will add that this book has some overlaps with several books, as is unavoidable when treating foundational material.

I certainly followed the path already taken by others in many of the basic proofs which seem to have reached a degree of perfection and upon which it is not possible to improve.

The names of the mathematicians who have given important contributions to Lie theory are many, and I have limited to a minimum the discussion of its history. The interested reader can now consult several sources like [Bor2], [GW].

I wish finally to thank Laura Stevens for carefully reading through a preliminary version and helping me to correct several mistakes, and Alessandro D'Andrea, Figà Talamanca and Paolo Papi for useful suggestions, and Ann Kostant and Martin Stock for the very careful and complex editing of the final text.

Claudio Procesi Università di Roma La Sapienza July 2006

### **Conventional Notations**

When we introduce a new symbol or definition we will use the convenient symbol := which means that the term introduced on its left is defined by the expression on its right.

A typical example could be  $P := \{x \in \mathbb{N} \mid 2 \text{ divides } x\}$ , which stands for P is by definition the set of all natural numbers x such that 2 divides x.

The symbol  $\pi : A \to B$  denotes a mapping called  $\pi$  from the set A to the set B.

Most of our work will be for algebras over the field of real or complex numbers. Sometimes we will take a more combinatorial point of view and analyze some properties over the integers. Associative algebras will implicitly be assumed to have a unit element. When we discuss matrices over a ring A we always identify A with the scalar matrices (constant multiples of the identity matrix).

We use the standard notations:

 $\mathbb{N}, \mathbb{Z}, \mathbb{Q}, \mathbb{R}, \mathbb{C}$ 

for the natural numbers (including 0), the integers, rational, real and complex numbers.